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A MIXED INTEGER LINEAR PROGRAMMING FORMULATION FOR LOW DISCREPANCY CONSECUTIVE K-SUMS PERMUTATION PROBLEM

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Abstract: In this paper, low discrepancy consecutive k-sums permutation problem is considered. A mixed integer linear programing (MILP) formulation with a moderate number of variables and constraints is proposed. The correctness proof shows that the proposed formulation is equivalent to the basic definition of low discrepancy consecutive k-sums permutation problem. Computational results, obtained on standard CPLEX solver, give 88 new exact values, which clearly show the usefulness of the proposed MILP formulation.

Keywords: Mixed Integer Linear Programming, Permutations with Low Discrepancy Consecutive k-sums.

MSC: 90C10, 68R10.

1. INTRODUCTION

Our description of the problem can start with the question, and its answer, as given in [1]: "Is it possible to arrange the integers 1 through n on a circle so that, for a given k, any sum of k consecutive integers on the circle is close to the expected value of $\frac{k \cdot (n+1)}{2}$? We can do it remarkably well."

1.1. Problem defintion

Let n and k be positive integers such that $k \le n$, and S_n is a set of all permutations $\pi = (\pi_1, \pi_2, ..., \pi_n)$ of the set $\{1, 2, ..., n\}$ viewed as a circle, i.e. indices are always evaluated by modulo n. So, low discrepancy consecutive k-sums permutation problem (LDCkSPP) can be formulated as follows.

$$disc(n,k) = \min_{\pi \in S_n} disc(\pi,k)$$
 (1)

where

$$disc(\pi, k) = \max_{1 \le i \le n} \left| -\frac{k \cdot (n+1)}{2} + \sum_{j=1}^{k} \pi_{i+j} \right|$$
 (2)

It is easy to see that the only case when disc(n,k) = 0 is if n = k, while disc(n,k) > 0 for all k < n. Also, disc(n,k) and disc(n,n-k) are complementary, so it is enough to consider only the case that $k \le \frac{n}{2}$. Moreover, when n is even and k is odd then $disc(n,k) \in \{0.5 + m \mid m \in Z, m \ge 0\}$, while $disc(n,k) \in N$, otherwise.

Example 1. For n = 5 and k = 2, permutation $\pi = (1, 4, 3, 2, 5)$ has the corresponding consecutive 2-sums equal to 5, 7, 5, 7, 6, respectively. Since $\frac{k\cdot(n+1)}{2} = 6$ then, $disc(\pi, 2) = 1$, which is obviously the optimal solution, since for odd n or even k, $disc(n, k) \in N$.

1.2. Previous work

Anstee et al. (2002) in [1] give many theoretical results about permutation discrepancy. They find that, in general, the discrepancy is small, never more than k+6, and independent of n. For g=gcd(n,k)>1, they proved the upper bound of $\frac{7}{2}$, while for g=1, the result is more complicated, which is presented in Table 2. Their constructions show that $disc(n,k) \leq \frac{k}{2} + 9$ for large n, while it is at least $\frac{k}{2}$ for infinitely many n. They also give some theoretical results regarding easier case of linear permutations (non-cyclic).

Stefanović (2010) in [2] determined exact values of disc(n,k) for small n,k using branch-and-bound technique. Exact values are reported, for k up to 10, and for n up to several tenths. Additionally, upper and lower bounds, for k up to 10, and for n up to 100, obtained by theoretical results from the literature are presented.

Stefanović and Živković (2015) in [3] proved that disc(6t+3,3) = 2, completing previously known results about disc(n,3). They also found that disc(2kt,k) = 1.5, for odd k and t > 1.

Ref.	Conditions	disc(n, k)
[1]	n = 2k, k odd	0.5
	n = 3k, k odd	1
	$n \ge 3, k = 2$	1
	n = 3k, k odd	1
	$k \text{ even, } n = \pm 1 \pmod{k}$	$\frac{k}{2}$
[3]	$n = 2kt, k \text{ odd}, t > 1, t \in N$	1.5
	$n = 6t + 3, k = 3, t \ge 2, t \in N$	2

Table 1: Theoretical exact values from the literature

Table 2: Theoretical bounds from the literature

Ref.	Conditions	Bound
[1]	<i>n</i> ≥ 6	$disc(n,3) \leq 2$
		$disc(n,pq) \le p \cdot disc(n,q)$
	<i>k</i> even	$disc(n,k) \leq \frac{k}{2}$
	k odd	$disc(mk, k) \leq 2$
	g > 1, g even	$disc(n,k) \leq 2$
	g > 1, g odd	$disc(n,k) \leq 3.5$
	g > 1, g odd	$disc(n,k) \leq disc(\frac{n}{q},\frac{k}{q})$
	$g=1, n>2k, r\geq 1,$	$disc(n,k) \geq \frac{k}{2s}$
	k odd, g = 1	$disc(n,k) \le k+6$
	$k \text{ odd}, g = 1, n > n_0(k)$	$disc(n,k) \le \frac{k}{2} + 9$

1.3. Theoretical results from literature

The concise survey of theoretical exact values about disc(n, k) in the literature is given in Table 1. The first column contains the reference to the paper in which the theoretical result is introduced, the second column lists the conditions, while the third column gives the exact values of disc(n, k).

Table 2, which is organized in a similar way as Table 1, contains the lower or upper bounds of disc(n, k). In Table 2, the following denotations are used:

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g denotes gcd(n,k), i.e. greatest common divisor of n and k;
r denotes the residue of division of n by k, i.e. r \equiv n \pmod{k};
s denotes the smallest positive integer for which holds r \cdot s \equiv \pm 1 \pmod{k}.
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2. PROPOSED MILP FORMULATION

As it is suggested in literature, it is useful to represent various mathematical problems as integer programming problems in order to use different well-known optimization techniques. Following that idea, we will introduce a mixed linear programming (MILP) formulation of the present problem in order to give theoretical and practical insights and to compare to with the previous branch-and-bound techniques, proposed in the literature.

Let π be the permutation. Decision variables x_{ij} can be defined as:

$$x_{ij} = \begin{cases} 1, & j = \pi_i \\ 0, & j \neq \pi_i \end{cases} \tag{3}$$

and

$$z = disc(\pi, k) = \max_{1 \le i \le n} \left| -\frac{k \cdot (n+1)}{2} + \sum_{j=1}^{k} \pi_{i+j} \right|$$
 (4)

The mixed integer linear programming formulation for solving the low discrepancy consecutive k-sums permutation problem can be stated as:

$$min z$$
 (5)

subject to:

$$\sum_{j=1}^{n} x_{ij} = 1 i = 1, ..., n (6)$$

$$\sum_{i=1}^{n} x_{ij} = 1 j = 1, ..., n (7)$$

$$\frac{k(n+1)}{2} + z \ge \sum_{i=i+1}^{i+k} \sum_{l=1}^{n} l \cdot x_{jl} \qquad i = 1, ..., n$$
 (8)

$$\frac{k(n+1)}{2} - z \le \sum_{j=i+1}^{i+k} \sum_{l=1}^{n} l \cdot x_{jl} \qquad i = 1, ..., n$$
 (9)

$$x_{ij} \in \{0, 1\}$$
 $i, j = 1...n$ (10)

$$z \in [0, +\infty) \tag{11}$$

The objective function (5) minimizes the discrepancy, defined by constraints (8) and (9). Constraints (6) and (7) ensure that variables x_{ij} represent a permutation, while (10) and (11) reflect the nature of decision variables x_{ij} and variable z.

The presented MILP model has n^2 binary variables, one continuous, and $4 \cdot n$ constraints. The equivalence of the proposed MILP model (5)-(11) with the basic mathematical formulation (1)-(2) is proved in Theorem 1.

Theorem 1. A low discrepancy consecutive k-sums permutation defined by (1)-(2) is optimal if and only if constraints (5)-(11) are satisfied.

Proof. (\Rightarrow) Suppose that π is an optimal low discrepancy consecutive k-sums permutation for fixed n and k. Let variables x_{ij} be defined as in (3), and z is defined as in (4). It means that variables x_{ij} are binary and z is continuous, so constraints (10) and (11) are satisfied by default.

¿From the definition of variables x_{ij} , and the fact that π is well-defined function, it holds that $(\forall i)(\exists_1 j) \ j = \pi_i$,

$$x_{i,\pi_i} = 1 \tag{12}$$

and

$$(\forall j \neq \pi_i) \ x_{ij} = 0, \tag{13}$$

which means $\sum_{i=1}^{n} x_{ij} = 1$ implying that constraints (6) are satisfied.

Similarly, π is permutation, so there exist the inverse permutation π^{-1} . From $(\forall j)(\exists_1 i) \ \pi_j^{-1} = i$, it follows $x_{\pi_j^{-1},j} = 1$, while $(\forall i \neq \pi_j^{-1}) \ x_{ij} = 0$, which means $\sum_{i=1}^{n} x_{ij} = 1, \text{ so constraints (7) are satisfied.}$ Let fix $j \in \{1, 2, ..., n\}$. As it can be seen in (13), $(\forall l \neq \pi_j) \ x_{jl} = 0$, so $(\forall l \neq \pi_j) \ x_{jl} = 0$,

 π_j) $l \cdot x_{jl} = 0$, implying $\sum_{l=1,l \neq \pi_i}^n l \cdot x_{jl} = 0$. Since by (12) $x_{j,\pi_j} = 1$, then it holds

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which means $(\forall i) \frac{k \cdot (n+1)}{2} + z \ge \sum_{j=i+1}^{i+k} \pi_j$. In the previous paragraph, it is proven that

 $\pi_j = \sum_{l=1}^n l \cdot x_{jl}$, so we can replace π_j with $\sum_{l=1}^n l \cdot x_{jl}$. The first term is equivalent to

 $(\forall i) \frac{k \cdot (n+1)}{2} + z \ge \sum_{j=i+1}^{i+k} \sum_{l=1}^{n} l \cdot x_{jl}$, which exactly represents constraints (8). Similarly, the

second term is equivalent to $(\forall i)$ $z \ge \frac{k \cdot (n+1)}{2} - \sum_{j=1}^k \pi_{i+j}$, implying $(\forall i)$ $\sum_{j=1}^k \pi_{i+j} \ge \frac{k \cdot (n+1)}{2} - \sum_{j=1}^k \pi_{i+j}$

z. Finally, when we replace π_j with $\sum_{l=1}^n l \cdot x_{jl}$ it holds $(\forall i)$ $\sum_{j=i+1}^{i+k} \sum_{l=1}^n l \cdot x_{jl} \ge \frac{k \cdot (n+1)}{2} - z$ which is equivalent to constraints (9). Moreover, from $z = disc(\pi, k)$ and the fact

which is equivalent to constraints (9). Moreover, from $z = aisc(\pi, k)$ and the fact that the objective function (5) is minimum of z, it holds that objective function value of MILP formulation (5)-(11) is less than or equal to the value of minimal low discrepancy consecutive k-sums permutation.

(⇐) For fixed $i \in \{1, 2, ..., n\}$, let π_i be defined as $\pi_i = j$ if $x_{ij} = 1$. From constraints (10) it follows that variable x_{ij} has binary nature, which, with constraints (6), implies that $(\forall i)$ $\sum_{j=1}^{n} x_{ij} = 1 \Rightarrow (\forall i)(\exists_1 j) x_{ij} = 1$, so π is a well-defined function.

Similarly, from constraints (10) and (7), it follows $(\forall j)$ $\sum_{i=1}^{n} x_{ij} = 1 \Rightarrow (\forall j)(\exists_1 i) x_{ij} = 1$, so π is bijection. Since $\pi : \{1, 2, ..., n\} \rightarrow \{1, 2, ..., n\}$, it means that π is permutation.

From the definition of permutation π , it means that $\sum_{l=1}^{n} l \cdot x_{jl} = \pi_j \cdot x_{j\pi_j} = \pi_j$, since $x_{j,\pi_j} = 1$. Therefore, from constraints (8) and (9), it holds $(\forall i) \frac{k(n+1)}{2} - z \le \sum_{j=i+1}^{i+k} \pi_j \le \frac{k(n+1)}{2} + z$. The last term is equivalent to $z \ge \frac{k(n+1)}{2} - \sum_{j=i+1}^{i+k} \pi_j$ and $z \ge -\frac{k(n+1)}{2} + \sum_{j=i+1}^{i+k} \pi_j$, which means $z \ge \left| -\frac{k(n+1)}{2} + \sum_{j=i+1}^{i+k} \pi_j \right| = \left| -\frac{k(n+1)}{2} + \sum_{j=1}^{k} \pi_{i+j} \right|$. Therefore, $(\forall i) \ z \ge \left| -\frac{k(n+1)}{2} + \sum_{j=1}^{k} \pi_{i+j} \right| \Rightarrow$

 $z \ge \max_{1 \le i \le n} \left| -\frac{k \cdot (n+1)}{2} + \sum_{j=1}^k \pi_{i+j} \right|$, implying $z \ge disc(\pi,k)$. Moreover, from $disc(\pi,k) \le z \Rightarrow disc(n,k) = \min_{\pi \in S_n} disc(\pi,k) \le z$, it holds that the value of minimal low discrepancy consecutive k-sums permutation is smaller than or equal to the optimal value of MILP formulation (5)-(11).

Therefore, the minimal value of low discrepancy consecutive k-sums permutation is equal to the optimal value of MILP formulation (5)-(11). \Box

3. COMPUTATIONAL RESULTS

In this section, experimental results obtained by the CPLEX 12.5.1 solver, using proposed MILP formulation will be presented. All computations were executed

UB ИВ UВ 0.0/8 0.218 0.562 0.203 0.812 2.500 20.83 40 35 34 35 37 38 24 25 29 31 33 34 35 39 22 23 24 26 27 28 2 5.5 3.218 4.171 8.390 5.140 31 34 35 39 0.312 23.03 655.9 26 27 28 29 30 31 32 33 34 38 35 36 37 39 34 366.7 1.890 110.5 61.84 1467 7.656 7.906 7.078 32.66 128.0 65.17 35 36 38 39 6.406 940.3 37.50 797.0 927.3 1.859 61.38 7231 3.000 219.7 377.2 340.6 35 37 30 31

Table 3: New exact values of disc(n, k)

on HP i5-3470, 3.2GHz PC with 8GB RAM, using single core. The MILP model used by CPLEX 12.5.1 solver was coded in C programming language.

In order to clearly present the effectiveness of the proposed MILP formulation, all previously known exact solutions are omitted, so Table 3 contains only data for new exact values of disc(n,k). It should be mentioned that branch-and-bound approach [2] obtained optimal value disc(56,4) = 1, while CPLEX based on the presented model could not obtain an exact result in 7200 seconds. In the first two columns the n and k are given. The third and fourth columns are labeled with LB and LB and present the values of lower and upper bound, taken from the literature. The fifth and the sixth column are labeled with Opt and t, containing the corresponding optimal solution values and total running time (in seconds), obtained by CPLEX 12.5.1 solver. The following six columns have the same meaning as the first six columns.

Experimental results given in Table 3 show that 88 new exact values of disc(n, k), with various n and k, are obtained. Although running time can be large (for example, in the case n = 40, k = 6 CPLEX needs 10131 seconds which is almost 3 hours), many results are obtained in less than 10 seconds. Advantages of the presented model over the previous exact approaches are more visible for large k values.

4. CONCLUSIONS

This paper is devoted to the low discrepancy consecutive k-sums permutation problem. The mixed integer linear programing formulation with a moderate

number of variables and constraints is introduced. We also give the formal proof that the proposed model is equivalent to the basic problem definition. From computational results, it is evident that the proposed model has theoretical and practical significance.

One direction for future work can be to design an exact method by using the proposed MILP formulation. The second direction may be solving some similar problems.

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